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Demo: Replication Sutton & Barto, Reinforcement Learning: An Introduction, Chapter 2 Robin van Emde 2020-07-25 Source: vignettes/sutton_barto.Rmd. sutton_barto.Rmd. Simulation of the multi-armed Bandit examples in chapter 2 of “Reinforcement Learning: An Introduction” by Sutton and Barto, 2nd ed. (Version: 2018)

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reinforcement learning problem whose solution we explore in the rest of the book. Part II presents tabular versions (assuming a small nite state space) of all the basic solution methods based on estimating action values. We intro-duce dynamic programming, Monte Carlo methods, and temporal-di erence learning.

[Reinforcement Learning: An Introduction](#)
A master chess player makes a move. ... known as the actor-critic architecture, and applied this method to Michie and Chambers's pole-balancing problem (Barto, Sutton, and Anderson, 1983). ... The classical solution to balancing exploration and exploitation in n-armed bandit problems is to compute special functions called Gittins indices.

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Also on his site Sutton says that if you send your attempt for a chapter to him he will send you solutions. I'm sure he won't judge your answers - he probably just wants feedback. (Or maybe he doesn't have answers yet :p)

[Solutions of Reinforcement Learning An Introduction Sutton ...](#)
Richard S. Sutton and Andrew G. Barto Second Edition (see here for the first edition) MIT Press, Cambridge, MA, 2018. Buy from Amazon Errata and Notes Full Pdf Without Margins Code Solutions-- send in your solutions for a chapter, get the official ones back (currently incomplete) Slides and Other Teaching Aids

[Sutton & Barto Book: Reinforcement Learning: An Introduction](#)
In Reinforcement Learning, Richard Sutton and Andrew Barto provide a clear and simple account of the key ideas and algorithms of reinforcement learning. Their discussion ranges from the history of the field's intellectual foundations to the most recent developments and applications.

[Introduction to Reinforcement Learning | Guide books](#)
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Singh & Sutton, 1996; Sutton, 1995). Gullapalli and Barto (1994) and Jalali and Ferguson (1989) presented algorithms that learn a model of the environment from experience, perform value iteration on the estimated model, and with infinite exploration converge to the optimal policy asymptotically.

[Near-Optimal Reinforcement Learning in Polynomial Time](#)
Richard S. Sutton and Andrew G. Barto MIT Press, Cambridge, MA, 1998 A Bradford Book Endorsements Code Solutions Figures Errata Course Slides This introductory textbook on reinforcement learning is targeted toward engineers and scientists in artificial intelligence, operations research, neural networks, and control

Reinforcement Learning, second edition Mobile Speech and Advanced Natural Language Solutions Reinforcement Learning and Optimal Control Algorithms for Reinforcement Learning Artificial Intelligence and Inclusive Education Artificial Higher Order Neural Networks for Economics and Business Neural Networks for Control Reinforcement Learning Ant Colony Optimization Foundations of Computational Mathematics, Santander 2005 Advanced Deep Learning with Keras Deep Reinforcement Learning Hands-On An Introduction to Neural Networks Novelities in Intelligent Digital Systems Insights in Reinforcement Learning Machine Learning for Factor Investing: R Version Encyclopedia of Machine Learning Advanced Finite Element Methods and Applications Advances in Neural Information Processing Systems 15 Deep Reinforcement Learning
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