

Applied Nonlinear Control Slotine Jean Jacques

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Control Meets Learning Seminar by Jean-Jacques Slotine (MIT) | Dec 2, 2020 **Jean-Jacques Slotine – Collective computation in nonlinear networks and the grammar of evolvability**

Nonlinear Control:A Charming (u0026 Adventurous Voyage by Alberto Isidori: The 2nd Wook Hyun Kwon Lecture 2Basic Lyapunov Theory Nonlinear Systems **Panel Discussion Stability using Describing Functions** (u0026 Limit Cycles) Nonlinear Control Systems 6.2 Nonlinear Control University of Pennsylvania Coursea *Feedback Linearization | Input State Linearization | Nonlinear Control Systems* Nonlinear Systems Overview Introduction | Nonlinear Control Systems **Sparse Identification of Nonlinear Dynamics for Model Predictive Control** 06Feedback Linearization | by Prof Ravi N Bannur, IIT Bombay Understanding Model Predictive Control, Part 1: Why Use MPC? Linear Systems Theory **Trimming and Linearization, Part 4 – What is Linearization?** Intro to Control – 5.2 System Linearization Understanding Model Predictive Control, Part 4 – Adaptive Gain Scheduled and Nonlinear MPC **Sliding Mode Control of a Ball on Wheel System Stability of Systems + Nonlinear Control Systems** **Introduction to Nonlinear Control System Networked! The Hidden System Behind Everything | Albert-László Barabási at Brain Bar**

Intro to Control - 4.3 Linear Versus Nonlinear Systems*Big Data 2017 | Albert-László Barabási Lecture 33: Sliding Mode Control Introduction to Sliding Mode Observers* – Lecture by Samh K Spurgeon *Feedback Linearization Overview Lecture 8 | Normalization, Regularization etc. pt2 Success Is Not About You | The Laws of Success with Albert-László Barabási* Applied Nonlinear Control Slotine Jean By Jean-Jacques Slotine - Applied Nonlinear Control: 1st (first) Edition Paperback. 22 offers from \$91.09. Data-Driven Science and Engineering: Machine Learning, Dynamical Systems, and Control Steven L. Brunton. 4.8 out of 5 stars 70. Hardcover. \$61.48. Next.

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The Nonlinear Systems Laboratory is headed by Professor Jean-Jacques Slotine. Members and affiliates are Nick Boffi (boffi@g.harvard.edu) Brett Lopez (blopez@mit.edu)

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'Jean-Jacques Slotine?' - ?Google Scholar?

Textbook reference for lectures 1-13 is . Applied Nonlinear Control, Slotine and Li, Prentice-Hall 1991. Main references for lectures 14-20 are . R1 Lohmuller, W., and Slotine, J.J.E., "On Contraction Analysis for Nonlinear Systems," Automatica, 34(6), 1998 R2 Slotine, J.J.E., "Modular Stability Tools for Distributed Computation and Control," Int. J. Adaptive Control and Signal Processing, 17(6 ...

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Applied Nonlinear Control by Jean-Jacques Slotine

Professor Jean-Jacques Slotine is Professor of Mechanical Engineering and Information Sciences, Professor of Brain and Cognitive Sciences, and Director of the Nonlinear Systems Laboratory. He received his Ph.D. from the Massachusetts Institute of Technology in 1983, at age 23. After working at Bell Labs in the computer research department, he joined the faculty at MIT in 1984.

JEAN-JACQUES SLOTINE

Slotine minimizes a lot of that dense math and, in my opinion, focuses on the important concepts of nonlinear control without getting bogged down. On the negative side, as others have pointed out, Slotine's book doesn't have the detailed mathematical treatment of other books on nonlinear control.

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He is the coauthor of the textbooks Robot Analysis and Control (Wiley, 1986) and Applied Nonlinear Control (Prentice-Hall, 1991). Prof. Slotine was a member of the French National Science Council from 1997 to 2002, and of Singapore's A*STAR SigN Advisory Board from 2007 to 2010.

Jean-Jacques E. Slotine - IEEE Xplore Author Details

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